

DRIVES TECHNOLOGY

KOSTAL



Data sheet

INVEOR MC1

KOSTAL^{ize}

your application

INVEOR MC1 – Build your own System

INVEOR MC1

IP65 protection class
Robust and vibration-resistant housing

Bluetooth Stick
microSD card slot
Status LEDs

3~ AC : 0.55 – 4.0kW /
1~ AC : 0.55 – 2.2kW
Overload capacity up to 250 %

Specialized variants

MC101 - 104

Plugin option



2 relays



1-channel STO with relay



2-channel STO

Universal adaptation

Free choice of motor type:
manufacturer independence
Direct mounting on the motor
Cable glands
Optional connectors for
signal and power
Alternative wall mounting
possible

Motor control

Support for all synchronous reluctance,
synchronous and asynchronous motors
Sensorless control
Maximum energy efficiency

Housing options

IO extension (M12 connector)
Display*
Functionally safe
communication
(PROFIsafe/FSoE)*

Integrated functions

Vibration monitoring
Extensive signal inputs
and outputs
Universal brake control
Integrated soft PLC
Sensorless positioning
Optional braking resistor

* In preparation

Communication

CANopen

PROFINET

MODBUS RTU

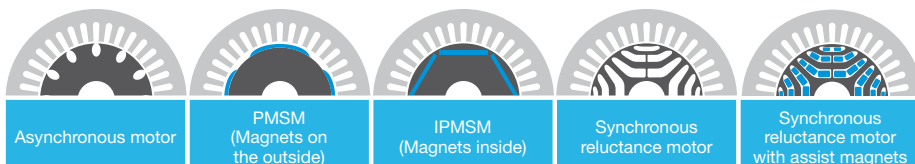
EtherNet/IP

EtherCAT

Bluetooth




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Technical data INVEOR MC1

3-phase frequency inverters

Size	A				B		
Recommended motor rating ¹⁾ [kW]	0.55	0.75	1.1	1.5	2.2	3	4
Supply voltage	3 x 200 V AC -10 %...480 V AC +10 % 280 V DC -10 %...680 V DC +10 % ²⁾						
Grid frequency	50/60 Hz ± 6%						
Network configurations	TN / TT / IT						
Line current [A]	1.4	1.9	2.6	3.3	4.6	6.2	7.9
Rated current output, eff. [IN at 4 kHz]	1.7	2.3	3.1	4	5.6	7.5	9.5
Min. brake resistance [Ω]	100				50		
Overload for 60 sec. [%]	200				200		
Overload for 3 sec. [%]	250		200		250		200
Switching frequency	Automatic regardless of temperature, 2 kHz, 4 kHz, 6 kHz, 8 kHz, 12 kHz, 16 kHz (factory setting 4 kHz)						
Output frequency	0 Hz – 1.000 Hz						
Mains cycles of operation / restart	unlimited ³⁾						
DIN EN 61800-9-2 touch current	< 3,5 mA ⁴⁾						
Protective function	Overvoltage and undervoltage, I ² t restriction, short-circuit, ground leak, motor and variable frequency drive temperature, stall prevention, blocking detection, PID dry run protection, functional safety (SIL 3/PLe)						
Software functions	Torque control ⁵⁾ , (PID controller), fixed frequencies, data record changeover, flying restart, motor current limit						
Soft PLC	IEC61131-3, FBD, ST, AWL						
Housing	Two-part aluminium die-cast housing						
Dimensions including standard adapter [L x W x H] mm	225.5 x 142.5 x 118				260 x 180 x 155		
Weight including standard adapter [kg]	2.3 kg				3.9 kg		
Protection class [IPxy]	IP65 / UL 50E Type 4X comparable to NEMA 4X						
Cooling	Passive Cooling						
Climate class (DIN EN 60721-3-3:1995)	3K3 (50°C)						
Ambient temperature	-30 °C (non condensing) up to +40 °C (+50 °C with derating)						
Storage temperature	-40 °C...+85 °C						
Altitude of the installation location	Up to 1000 m above sea level / over 1000 m with reduced performance (1 % per 100 m) / above 2000 m see operating manual						
Relative air humidity	≤ 96 %, condensation not permitted						
Vibration class (DIN EN 60721-3-3:1995) ⁶⁾	3M7 (3g)						
EMC (DIN-EN-61800-3)	C2 industrial sector						
Energy efficiency class (EN 61800-9-2)	IE2						
Certificates and conformity							

*In preparation

Technical data for INVEOR MC1 (subject to technical changes)

¹⁾ Recommended motor rating (4-pole asynchr. motor) is given based on the 400 V AC / 230 V AC supply voltage.

²⁾ In compliance with the overvoltage category.




³⁾ < 3s may result in power failure/intermediate circuit undervoltage faults.

⁴⁾ With 1LA7 asynchronous motor, motor-mounted.

⁵⁾ Only for synchronous and reluctance motors.

⁶⁾ Installation- and application-related resonant frequencies can damage the devices.

1-phase frequency inverters

Size	A			B	
Recommended motor rating ¹⁾ [kW]	0.55	0.75	1.1	1.5	2.2
Supply voltage	1 x 100 V AC -15 %...230 V AC +10 % 140 V DC -15 %...320 V DC +10 % ²⁾				
Grid frequency	50/60 Hz ± 6%				
Network configurations	TN / TT / IT				
Line current [A]	In preparation				
Rated current output, eff. [IN at 4 kHz]	In preparation				
Min. brake resistance [Ω]	In preparation				
Overload for 60 sec. [%]	200			150	
Switching frequency	Automatic regardless of temperature, 2 kHz, 4 kHz, 6 kHz, 8 kHz, 12 kHz, 16 kHz (factory setting 4 kHz)				
Output frequency	0 Hz – 1.000 Hz				
Mains cycles of operation / restart	every 2 minutes ³⁾				
DIN EN 61800-9-2 touch current	< 10 mA ⁴⁾				
Protective function	Overvoltage and undervoltage, I ² t restriction, short-circuit, ground leak, motor and variable frequency drive temperature, stall prevention, blocking detection, PID dry run protection, functional safety (SIL 3/PLe)				
Software functions	Torque control ⁵⁾ , (PID controller), fixed frequencies, data record changeover, flying restart, motor current limit				
Soft PLC	IEC61131-3, FBD, ST, AWL				
Housing	Two-part aluminium die-cast housing				
Dimensions including standard adapter [L x W x H] mm	225.5 x 142.5 x 118			260 x 180 x 155	
Weight including standard adapter [kg]	2.3 kg			3.9 kg	
Protection class [IPxy]	IP65 / UL 50E Type 4X comparable to NEMA 4X				
Cooling	Passive Cooling				
Climate class (DIN EN 60721-3-3)	3K3 (50°C)				
Ambient temperature	-30 °C (non condensing) up to +40 °C (+50 °C with derating)				
Storage temperature	-40 °C...+85 °C				
Altitude of the installation location	Up to 1000 m above sea level / over 1000 m with reduced performance (1 % per 100 m) / above 2000 m see operating manual				
Relative air humidity	≤ 96 %, condensation not permitted				
Vibration class (DIN EN 60721-3-3:1995) ⁶⁾	3M7 (3g)				
EMC (DIN-EN-61800-3)	C2				
Energy efficiency class (EN 61800-9-2)	IE2				
Certificates and conformity	  				

*In preparation

INVEOR MC1 – Specialized variants

INVEOR model MC101



X1	X2	X3	X4	X5
Potentiometer		USB-C		

INVEOR model MC102



X1	X2	X3	X4	X5
Potentiometer	Modbus/RS485	USB-C		CANopen

INVEOR model MC103



X1	X2	X3	X4	X5
	Modbus/RS485	USB-C	Ethernet	Ethernet

INVEOR model MC104



X1	X2	X3	X4	X5
DI1 + DI2	DIO1 + DIO2	USB-C	Ethernet	Ethernet

Features of the variants

INVEOR model	MC101	MC102	MC103	MC104
Digital input (DI)	4	4	4	2 via M12 connector to X1
Bidirectional digital I/O	2	2	2	2 via M12 connector to X2
Analog input (AI)	2	2	2	
Bidirectional analog I/O	1	1	1	
PT1000	1	1	1	
microSD card slot		1	1	1
Motor PTC	1	1	1	1
Rotary encoder	HTL via digital inputs		HTL via digital inputs	HTL via digital inputs
24V DC power supply	internal		internal / external	internal / external
Potentiometer	to X1			
USB-C	to X3		to X3	to X3
MODBUS RTU		via M12 to X2	via M12 to X2	
CANopen		via M12 to X5		
EtherNet/IP EtherCAT			via M12 to X4 and X5	via M12 to X4 and X5
Vibration monitoring			integrated	integrated
1-phase	Without brake control			
3-phase	With or without brake control			
Example applications	basic applications			
			mechanical engineering	
			intralogistics	

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